IRU Series Ultrasonic Sensors
User Manual

IRU-2000’s, IRU-3430’s, IRU-5000’s, IRU-6420’s, & IRU-9420’s
# Table of Contents

Introduction ................................................................................................................iii

Warranty and Warranty Restrictions ........................................................................iv

Chapter 1: Specifications and Options ................................................................. 1
  Dimensions ................................................................................................................. 1-2
  Specifications .............................................................................................................. 3-7
  Electrical Connectors and Pinout Tables ............................................................... 8
  Model Number Configurator ................................................................................... 9
  Wiring Diagrams ...................................................................................................... 10-12

Chapter 2: Installation and Removal Procedures and Notes ............................. 13
  Tools Needed ............................................................................................................. 13
  Installation Notes ..................................................................................................... 13-14
  Mounting Instructions ............................................................................................. 14
  Electrical Installation ............................................................................................... 15
  Software Installation ................................................................................................. 15
  Removal Instructions ............................................................................................... 15

Chapter 3: Set Up and Operation .......................................................................... 16
  User Interface ........................................................................................................... 16-18
  IRU Sensor Parameters .......................................................................................... 19-24
  Relay and NPN Trip Output Configuration ............................................................ 25-26
  Sensor Readings and Communication Status ....................................................... 26-28
  Control Buttons ...................................................................................................... 28-29
  Saving and Loading Parameter Files ..................................................................... 29

Chapter 4: Maintenance ......................................................................................... 30
  General Care ........................................................................................................... 30
  Troubleshooting ..................................................................................................... 30
  Calibration ............................................................................................................... 30-31
  Repair and Returns ................................................................................................. 31

Chapter 5: Hazardous Location Drawing and Certification ............................... 32
  Hazardous Location Drawing ................................................................................ 32
  CSA Certificate of Compliance ........................................................................... 33-35
Introduction

Thank you for purchasing an IRU ultrasonic sensor from APG. We appreciate your business! Please take a few minutes to familiarize yourself with your IRU and this manual.

The IRU series is APG’s line of general purpose ultrasonic sensors. With a choice of operating ranges from just a few inches to as far as 50 feet, the IRU product line is designed to fit a wide range of industrial automation applications. Sensor adjustments, such as sensitivity and filtering options, are made by interfacing the sensor to a PC using an RST module and APG’s free Windows based programming software. IRU sensors incorporate internal temperature compensation for increased accuracy under varying environmental conditions. The sensors are housed in PC/PET or UV resistant ABS to seal out moisture and resist a wide range of chemicals.

Reading your label

Every APG instrument comes with a label that includes the instrument’s model number, part number, serial number, and a wiring pinout table. Please ensure that the part number and pinout table on your label match your order. The following electrical ratings and approvals are also listed on the label. Please refer to the Certificate of Compliance and Declaration of Conformity at the back of this manual for further details.

Electrical ratings

Input: 12 to 28 Volts DC, 80mA max; Outputs: 4-20mA, NPN

Class I Division 2; Groups C, D T6
Class I, Zone 2, Group IIIB
AEx nA IIB T6: Ta: -30°C to 60°C; IP65
Ex nA IIB T6: Ta: -30°C to 60°C; IP65

IRU models: IRU-2423, IRU-2425, IRU-3433, IRU-3435, IRU-5413, IRU-5415, IRU-5423, IRU-5425.
Models listed are rated for Pollution Degree 2, Installation Category II.

Input: 12 to 28 Volts DC, 80 mA max; Outputs: 4-20mA, solid state relay, NPN
Listed for General Purpose
Ta: -30°C to 60°C;

Models listed are rated for Pollution Degree 2, Installation Category II.

IMPORTANT: Your IRU must be listed above and installed as shown on drawing 9003066 to meet listed approvals. Faulty installation will invalidate all safety approvals and ratings.
Warranty and Warranty Restrictions

This product is covered by APG’s warranty to be free from defects in material and workmanship under normal use and service of the product for 24 months. For a full explanation of our Warranty, please visit https://www.apgsensors.com/about-us/terms-conditions. Contact Technical Support to receive a Return Material Authorization before shipping your product back.

Scan the QR code below to read the full explanation of our Warranty on your tablet or smartphone.
Chapter 1: Specifications and Options

• Dimensions

IRU-200x

IRU-242x & IRU-642x

IRU-343x
## Specifications

**IRU-200X and 242X**

### Performance

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Range</td>
<td>1 - 25 ft. (0.3 - 7.6 m) on liquids and hard, flat surfaces</td>
</tr>
<tr>
<td></td>
<td>1 - 10 ft. (0.3 - 3 m) on bulk solids</td>
</tr>
<tr>
<td>Analog Output</td>
<td>1 Solid State Relay, Isolated 4-20 mA, 4-20 mA,</td>
</tr>
<tr>
<td></td>
<td>4-20 mA with 2 NPN Trip Points, 0-2.5 VDC / 0-5 VDC</td>
</tr>
<tr>
<td>Digital Output</td>
<td>RS-485 with 1 NPN Trip Point, RS-232 option</td>
</tr>
<tr>
<td>Display Output</td>
<td>For interface with APG digital display (IRU-2002, IRU-2003 only)</td>
</tr>
<tr>
<td>Beam Pattern</td>
<td>9° off axis</td>
</tr>
<tr>
<td>Transducer Frequency</td>
<td>69 kHz</td>
</tr>
<tr>
<td>Response Time</td>
<td>Programmable, 55 ms min @ 25 ft. (or 18 Hz max)</td>
</tr>
</tbody>
</table>

### Accuracy

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>Accuracy</td>
<td>±0.25% of detected range</td>
</tr>
<tr>
<td>Resolution</td>
<td>0.1 inch (2.54 mm)</td>
</tr>
</tbody>
</table>

### Environmental

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Temperature</td>
<td>-40 to 60°C  (-40 to 140°F)</td>
</tr>
<tr>
<td>Internal Temperature</td>
<td>Yes</td>
</tr>
<tr>
<td>Compensation</td>
<td></td>
</tr>
<tr>
<td>Enclosure Protection</td>
<td>IP65 (IRU-242X)</td>
</tr>
<tr>
<td>NEMA rating</td>
<td>4X (IRU-2000X only)</td>
</tr>
<tr>
<td>CSA Certifications</td>
<td>See page iii (IRU-242X only)</td>
</tr>
</tbody>
</table>

### Electrical

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operational Supply Voltage</td>
<td>12-28 VDC</td>
</tr>
<tr>
<td>Excitation Supply Voltage</td>
<td>5 VDC min. (0-2.5 / 0-5 VDC output only)</td>
</tr>
<tr>
<td>Programming Supply Voltage</td>
<td>15-28 VDC (12-28 VDC via RS-232)</td>
</tr>
<tr>
<td>Current Draw</td>
<td>80 mA max @ 24 VDC and 4 Hz  (IRU-200X)</td>
</tr>
<tr>
<td></td>
<td>75 mA max @ 24 VDC and 4 Hz  (IRU-242X)</td>
</tr>
<tr>
<td>Current Output</td>
<td>300 mA max (NPN Trip Points)</td>
</tr>
<tr>
<td></td>
<td>130 mA max (SSR, 120 VDC or VAC)</td>
</tr>
</tbody>
</table>

### Materials of Construction

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>Transducer Housing</td>
<td>ABS with UV inhibitor (IRU-200X)</td>
</tr>
<tr>
<td>Upper Housing</td>
<td>PVDF (Kynar®) (IRU-242X)</td>
</tr>
<tr>
<td>Transducer Type</td>
<td>PC/PET (IRU-242X)</td>
</tr>
<tr>
<td></td>
<td>ABS (IRU-200X)</td>
</tr>
<tr>
<td></td>
<td>Ceramic, PVDF faced (IRU-242X)</td>
</tr>
</tbody>
</table>

### Mounting

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Specifications</th>
</tr>
</thead>
<tbody>
<tr>
<td>IRU-200X</td>
<td>Surface Mount with Four Screws</td>
</tr>
<tr>
<td>IRU-242X</td>
<td>2” Ø NPT (front), 3/4” Ø NPT (rear)</td>
</tr>
</tbody>
</table>
IRU-343X

**Performance**
- Operating Range: 1.25 - 50 ft. (0.4 - 15.2 m)
- Analog Output: 4-20 mA
- 4-20 mA with 2 NPN Trip Points
- Digital Output: N/A
- Beam Pattern: 9° off axis
- Transducer Frequency: 43 kHz
- Response Time: Programmable, 100 ms min @ 50 ft. (or 10 Hz max)

**Accuracy**
- Accuracy: ±0.25% of detected range
- Resolution: 0.1 inch (2.54 mm)

**Environmental**
- Operating Temperature: -40 to 60°C (-40 to 140°F)
- Internal Temperature Compensation: Yes
- Enclosure Protection: IP65
- CSA Certifications: See page iii

**Electrical**
- Operational Supply Voltage (at sensor): 12-28 VDC
- Programming Supply Voltage: 15-28 VDC
- Current Draw: 75 mA max @ 24 VDC and 4 Hz

**Materials of Construction**
- Transducer Housing: PC/PET
- Upper Housing: PC/PET
- Transducer Type: Ceramic, PVDF faced

**Mounting**
- IRU-343X
- 3” Ø NPT (front), 3/4” Ø NPT (rear)
IRU-54XX

Performance
- Operating Range: 0.33 - 6.58 ft. (0.1 - 2.7 m)
- Analog Output: 4-20 mA
- 4-20 mA with 2 NPN Trip Points
- Digital Output: N/A
- Beam Pattern: 9° off axis
- Transducer Frequency: 143 kHz
- Response Time: Programmable, 22 ms min @ 6.58 ft. (or 45 Hz max)

Accuracy
- Accuracy: ±0.25% of detected range
- Resolution: 0.1 inch (2.54 mm)

Environmental
- Operating Temperature: -40 to 60°C (-40 to 140°F)
- Internal Temperature Compensation: Yes
- Enclosure Protection: IP65
- CSA Certifications: See page iii (IRU-54XX only)

Electrical
- Operational Supply Voltage (at sensor): 12-28 VDC
- Excitation Supply Voltage: 5 VDC min. (0-2.5 / 0-5 VDC output only)
- Programming Supply Voltage: 15-28 VDC
- Current Draw: 75 mA max @ 24 VDC and 4 Hz
- Current Output: 300 mA max (NPN Trip Points)

Materials of Construction
- Transducer Housing: PC/PET
- Upper Housing: PC/PET
- Transducer Type: Ceramic, PVDF faced

Mounting
- IRU-541X: 1” Ø NPT (front), 3/4” Ø NPT (rear)
- IRU-542X: 2” Ø NPT (front), 3/4” Ø NPT (rear)
IRU-642X

Performance
Operating Range 1.0 - 30.0 ft. (0.3 - 9.1 m)
Analog Output 0-2.5 VDC / 0-5 VDC
Digital Output RS-232 option
Beam Pattern 9° off axis
Transducer Frequency 69 kHz
Response Time Programmable, 64 ms min @ 30 ft. (or 15 Hz max)

Accuracy
Accuracy ±0.25% of detected range
Resolution 0.1 inch (2.54 mm)

Environmental
Operating Temperature -40 to 60°C (-40 to 140°F)
Internal Temperature Compensation Yes
Enclosure Protection IP65

Electrical
Operational Supply Voltage (at sensor) 12-28 VDC
Excitation Supply Voltage 5 VDC min.
Programming Supply Voltage 15-28 VDC
Current Draw 75 mA @ 24 VDC and 4 Hz
Serial Communications RS-232 (IRU-6429S only)
9600 baud, 8 bit, 1 stop bit, No parity

Materials of Construction
Transducer Housing PVDF (Kynar®)
Upper Housing PC/PET
Transducer Type Ceramic, PVDF faced

Mounting
IRU-642X 2” Ø NPT (front), 3/4” Ø NPT (rear)
## IRU-942X

### Performance
- **Operating Range**: 0.5 - 35 ft. (0.2 - 10.7 m)
- **Analog Output**: 4-20 mA
- **Analog Output with 2 NPN Trip Points**: 4-20 mA
- **Digital Output**: 0-2.5 VDC / 0-5 VDC
- **Beam Pattern**: 9° off axis
- **Transducer Frequency**: 50 kHz
- **Response Time**: Programmable, 73 ms min @ 35 ft. (or 13 Hz max)

### Accuracy
- **Accuracy**: ±0.25% of detected range
- **Resolution**: 0.1 inch (2.54 mm)

### Environmental
- **Operating Temperature**: -40 to 60°C (-40 to 140°F)
- **Internal Temperature Compensation**: Yes
- **NEMA rating**: 12

### Electrical
- **Operational Supply Voltage (at sensor)**: 12-28 VDC
- **Excitation Supply Voltage**: 5 VDC min. (0-2.5 / 0-5 VDC output only)
- **Programming Supply Voltage**: 15-28 VDC
- **Current Draw**: 75 mA max @ 24 VDC and 4 Hz
- **Serial Communications**: RS-232 (IRU-9429S only)
  - 9600 baud, 8 bit, 1 stop bit, No parity

### Materials of Construction
- **Transducer Housing**: PC/PET
- **Upper Housing**: PC/PET
- **Transducer Type**: Electrostatic

### Mounting
- **IRU-942X**: 2” Ø NPT (front), 3/4” Ø NPT (rear)
## Electrical Connectors and Pinout Tables

### IRU-2002

<table>
<thead>
<tr>
<th>3/C Cable</th>
<th>IRU-XXX3-C</th>
</tr>
</thead>
<tbody>
<tr>
<td>Red</td>
<td>+24 VDC</td>
</tr>
<tr>
<td>Black</td>
<td>DC Ground</td>
</tr>
<tr>
<td>White</td>
<td>4-20 mA Out</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>4-pin MC</th>
<th>IRU-XXX3-M</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 Brown</td>
<td>+24 VDC</td>
</tr>
<tr>
<td>2 White</td>
<td>Not used</td>
</tr>
<tr>
<td>3 Blue</td>
<td>DC Ground</td>
</tr>
<tr>
<td>4 Black</td>
<td>4-20 mA Out</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>6/C Cable</th>
<th>IRU-2004-C</th>
<th>IRU-2005-C</th>
</tr>
</thead>
<tbody>
<tr>
<td>Red</td>
<td>+24 VDC</td>
<td>+24 VDC</td>
</tr>
<tr>
<td>Black</td>
<td>DC Ground</td>
<td>DC Ground</td>
</tr>
<tr>
<td>Green</td>
<td>Clock Sync</td>
<td>Clock Sync</td>
</tr>
<tr>
<td>White</td>
<td>NPN trip</td>
<td>NPN 2</td>
</tr>
<tr>
<td>Blue</td>
<td>T (+) or (A)</td>
<td>NPN 1</td>
</tr>
<tr>
<td>Orange</td>
<td>T (-) or (B)</td>
<td>4-20 mA Out</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>5/C Cable</th>
<th>IRU-XXX5-C</th>
<th>IRU-XXX9-C</th>
</tr>
</thead>
<tbody>
<tr>
<td>Red</td>
<td>+24 VDC</td>
<td>+24 VDC</td>
</tr>
<tr>
<td>Black</td>
<td>DC Ground</td>
<td>DC Ground</td>
</tr>
<tr>
<td>Orange</td>
<td>4-20 mA Out</td>
<td>Excitation</td>
</tr>
<tr>
<td>Green</td>
<td>NPN 2</td>
<td>Analog Ground</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1 Brown</td>
<td>+24 VDC</td>
<td>+24 VDC</td>
<td>+24 VDC</td>
<td>+24 VDC</td>
</tr>
<tr>
<td>2 White</td>
<td>T (+) or (A)</td>
<td>NPN 1</td>
<td>NPN 1</td>
<td>Voltage Out</td>
</tr>
<tr>
<td>3 Blue</td>
<td>DC Ground</td>
<td>DC Ground</td>
<td>DC Ground</td>
<td>DC Ground</td>
</tr>
<tr>
<td>4 Black</td>
<td>T (-) or (B)</td>
<td>4-20 mA Out</td>
<td>4-20 mA Out</td>
<td>Analog Ground</td>
</tr>
<tr>
<td>5 Grey</td>
<td>NPN trip</td>
<td>NPN 2</td>
<td>NPN 2</td>
<td>Excitation</td>
</tr>
</tbody>
</table>

### IRU-2003

<table>
<thead>
<tr>
<th>8/C Cable</th>
<th>IRU-XXX9S-C</th>
</tr>
</thead>
<tbody>
<tr>
<td>Red</td>
<td>+24 VDC</td>
</tr>
<tr>
<td>Black</td>
<td>DC Ground</td>
</tr>
<tr>
<td>Orange</td>
<td>Excitation</td>
</tr>
<tr>
<td>White</td>
<td>Voltage Out</td>
</tr>
<tr>
<td>Green</td>
<td>Analog Ground</td>
</tr>
<tr>
<td>Brown</td>
<td>RS-232 Ground</td>
</tr>
<tr>
<td>Yellow</td>
<td>RS-232 TX</td>
</tr>
<tr>
<td>Blue</td>
<td>RS-232 RX</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>8-pin MC</th>
<th>IRU-XXX9S-M</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 White</td>
<td>Voltage Out</td>
</tr>
<tr>
<td>2 Brown</td>
<td>+24 VDC</td>
</tr>
<tr>
<td>3 Green</td>
<td>Analog Ground</td>
</tr>
<tr>
<td>4 Yellow</td>
<td>RS-232 TX</td>
</tr>
<tr>
<td>5 Grey</td>
<td>RS-232 Ground</td>
</tr>
<tr>
<td>6 Pink</td>
<td>RS-232 RX</td>
</tr>
<tr>
<td>7 Blue</td>
<td>DC Ground</td>
</tr>
<tr>
<td>8 Red</td>
<td>Excitation</td>
</tr>
</tbody>
</table>
**Model Number Configurator**

The IRU sensor series offers a wide range of housing, outputs, and performance specifications. Please refer to each sensor family's datasheet for a full list of available configurations. Datasheets can be found at [http://apgsensors.com/support](http://apgsensors.com/support).

<table>
<thead>
<tr>
<th>Model</th>
<th>Range</th>
<th>Frequency</th>
<th>Mounting</th>
<th>Output</th>
</tr>
</thead>
<tbody>
<tr>
<td>2002</td>
<td>1-25 ft / 0.3-7.6 m</td>
<td>69kHz</td>
<td>Surface/Screws</td>
<td>(1) Solid-State Relay</td>
</tr>
<tr>
<td>2003</td>
<td>1-25 ft / 0.3-7.6 m</td>
<td>69 kHz</td>
<td>Surface/Screws</td>
<td>Isolated 4-20mA</td>
</tr>
<tr>
<td>2004</td>
<td>1-25 ft / 0.3-7.6 m</td>
<td>69 kHz</td>
<td>Surface/Screws</td>
<td>RS-485, 1 NPN Trip</td>
</tr>
<tr>
<td>2005</td>
<td>1-25 ft / 0.3-7.6 m</td>
<td>69 kHz</td>
<td>Surface/Screws</td>
<td>4-20mA, 2 NPN Trip</td>
</tr>
<tr>
<td>2009S</td>
<td>1-25 ft / 0.3-7.6 m</td>
<td>69 kHz</td>
<td>Surface/Screws</td>
<td>0-2.5/0-5 VDC, RS-232</td>
</tr>
<tr>
<td>2423</td>
<td>1-25 ft / 0.3-7.6 m</td>
<td>69 kHz</td>
<td>2” NPT Threads</td>
<td>4-20mA</td>
</tr>
<tr>
<td>2425</td>
<td>1-25 ft / 0.3-7.6 m</td>
<td>69 kHz</td>
<td>2” NPT Threads</td>
<td>4-20mA, 2 NPN Trip</td>
</tr>
<tr>
<td>3433</td>
<td>1.25-50 ft / 0.4-15.2 m</td>
<td>43 kHz</td>
<td>3” NPT Threads</td>
<td>4-20mA</td>
</tr>
<tr>
<td>3435</td>
<td>1.25-50 ft / 0.4-15.2 m</td>
<td>43 kHz</td>
<td>3” NPT Threads</td>
<td>4-20mA, 2 NPN Trip</td>
</tr>
<tr>
<td>5413</td>
<td>0.33-6.56 ft / 0.1-2.7 m</td>
<td>143 kHz</td>
<td>1” NPT Threads</td>
<td>4-20mA</td>
</tr>
<tr>
<td>5415</td>
<td>0.33-6.56 ft / 0.1-2.7 m</td>
<td>143 kHz</td>
<td>1” NPT Threads</td>
<td>4-20mA, 2 NPN Trip</td>
</tr>
<tr>
<td>5419</td>
<td>0.33-6.56 ft / 0.1-2.7 m</td>
<td>143 kHz</td>
<td>1” NPT Threads</td>
<td>0-2.5/0-5 VDC</td>
</tr>
<tr>
<td>5423</td>
<td>0.33-6.56 ft / 0.1-2.7 m</td>
<td>143 kHz</td>
<td>2” NPT Threads</td>
<td>4-20mA</td>
</tr>
<tr>
<td>5425</td>
<td>0.33-6.56 ft / 0.1-2.7 m</td>
<td>143 kHz</td>
<td>2” NPT Threads</td>
<td>4-20mA, 2 NPN Trip</td>
</tr>
<tr>
<td>5429</td>
<td>0.33-6.56 ft / 0.1-2.7 m</td>
<td>143 kHz</td>
<td>2” NPT Threads</td>
<td>0-2.5/0-5 VDC</td>
</tr>
<tr>
<td>6429</td>
<td>1-30 ft / 0.3-9.1 m</td>
<td>69 kHz</td>
<td>2” NPT Threads</td>
<td>0-2.5/0-5 VDC</td>
</tr>
<tr>
<td>6429S</td>
<td>1-30 ft / 0.3-9.1 m</td>
<td>69 kHz</td>
<td>2” NPT Threads</td>
<td>0-2.5/0-5 VDC, RS-232</td>
</tr>
<tr>
<td>9423</td>
<td>0.5-35 ft / 0.2-10.7 m</td>
<td>50 kHz</td>
<td>2” NPT Threads</td>
<td>4-20mA</td>
</tr>
<tr>
<td>9425</td>
<td>0.5-35 ft / 0.2-10.7 m</td>
<td>50 kHz</td>
<td>2” NPT Threads</td>
<td>4-20mA, 2 NPN Trip</td>
</tr>
<tr>
<td>9429</td>
<td>0.5-35 ft / 0.2-10.7 m</td>
<td>50 kHz</td>
<td>2” NPT Threads</td>
<td>0-2.5/0-5 VDC</td>
</tr>
<tr>
<td>9429S</td>
<td>0.5-35 ft / 0.2-10.7 m</td>
<td>50 kHz</td>
<td>2” NPT Threads</td>
<td>0-2.5/0-5 VDC, RS-232</td>
</tr>
</tbody>
</table>
• **Wiring Diagrams**

**IRU-2003 Isolated 4-20 mA Source Wiring**

The IRU-2003 is equipped with an isolated 4-20 mA output. This means that the 4-20 mA circuit can be powered by the 4-20 mA signal receiver or a source independent of the receiver. An isolated source must be wired correctly to prevent potential ground loops that can exist in instances where the IRU and receiver are not sharing the same power source (See Figure 1.1). The 4-20 mA circuit can also be wired as a standard current sourcing 4-20 mA loop simply by powering the circuit from the same power source used by the main IRU sensor circuit (See Figure 1.2).

**Figure 1.1 - Isolated VDC Source Wiring**

**Figure 1.2 - Single VDC Source Wiring**

The IRU-2003 is equipped with an isolated 4-20 mA output. This means that the 4-20 mA circuit can be powered by the 4-20 mA signal receiver or a source independent of the receiver. An isolated source must be wired correctly to prevent potential ground loops that can exist in instances where the IRU and receiver are not sharing the same power source (See Figure 1.1). The 4-20 mA circuit can also be wired as a standard current sourcing 4-20 mA loop simply by powering the circuit from the same power source used by the main IRU sensor circuit (See Figure 1.2).
RST-3001/2 Programming Module Wiring

All IRU sensors (excluding the IRU-6429S and IRU-9429S) are fully programmable using an RST-3002 programming module, which acts as an interface between the sensor and a personal computer. The RST-3002 is both 32- and 64-bit Windows compatible.

The RST-3002 is connected in series between the sensor and its power source using the two 2-pin Phoenix connectors on the module (See Figure 1.3). 15-28 VDC from the power source is connected to one 2-pin connector, while the VDC + and DC Ground of the sensor is connected to the module through the second 2-pin connector. When power is applied, the red LED between the Phoenix connectors on the RST should illuminate and the sensor should start audibly “ticking”. The operating parameters of the sensor can then be adjusted using the Windows-based utility software.

NOTE: The utility software can be downloaded at www.apgsensors.com/support.
**Excitation Wiring for IRU-XXX9 Sensors**

![Excitation Wiring Diagram](image)

**Figure 1.4**

0-2.5 / 0-5 VDC IRU sensors include an +5 VDC Excitation input. (See Figure 1.4) If voltage is not applied at the Excitation input, the sensor will not communicate for programming, nor will it provide the 0-2.5 / 0-5 VDC output.

In essence, this allows for a small VDC supply, such as +5 VDC from a datalogger, to “wake” the sensor for output recording, and subsequently put the sensor back to “sleep.”

**IRU-200X Clock Synchronization Wiring**

![Clock Synchronization Wiring Diagram](image)

**Figure 1.5**

IRU-2002, IRU-2003, IRU-2004-C, and IRU-2005-C sensors are equipped with a clock synchronization to prevent cross-talk between sensors located in close proximity. When the clock sync terminals of two or more sensors are connected (See Figure 1.5), the output signals will synchronize. The sensors must share a common ground in order for the clock synchronization feature to function.
Chapter 2: Installation and Removal Procedures and Notes

• **Tools Needed**

Tools are necessary only for the screws used to install the surface mount IRU-200X, and to access the terminal strips inside IRU-2002 and IRU-2003 sensors. All other models can be mounted via NPT threads on the sensors.

If you are using a stand pipe to mount your IRU, you will probably need tools to install the stand pipe.

---

**NOTE:** Terminal strips for IRU-2002 and IRU-2003 sensors are internal to the sensor and must be connected before sensors are mounted.

---

![IRU-2002 Diagram](image1)

**Figure 2.1**

![IRU-2003 Diagram](image2)

**Figure 2.2**

Potentiometers for setting or adjusting *Trip Distance* (IRU-2002 only) and *Sensitivity* (IRU-2002 and IRU-2003) are located inside the sensor housing along with terminal strips (See Figures 2.1 and 2.2). Both settings can also be controlled via the I2000SWR software (See Figure 3.3).

---

• **Installation Notes**

- Mount your IRU sensor so that it has a clear, perpendicular sound path to the surface being monitored. Your sensor should be mounted away from tank or vessel walls and inlets. (See Figure 2.3)
- The sound path should be free from obstructions and as open as possible for the 9° off axis beam pattern.
- If you are using a stand pipe, please see our guide to stand pipes on our website: [http://www.apgsensors.com/about-us/blog/how-to-install-a-stand-pipe](http://www.apgsensors.com/about-us/blog/how-to-install-a-stand-pipe).
• **Mounting Instructions**

Mounting your IRU is easy if you follow a few simple steps:

- For IRU-200X sensors, use the necessary screws or bolts (not provided by APG) to mount the sensor.

For all other IRU models:

- Never over-tighten the sensor.
- Always screw in your sensor by hand to avoid cross-threading. Thread failure can be a problem if you damage threads by over-tightening them or by crossing threads.

**IMPORTANT:** Do not over tighten! The sensor should be threaded in only hand tight.
• **Electrical Installation**
  
  - Check the pinout table on your IRU against your order
  - Check that your electrical & control system wiring matches the pinout table on your IRU.
  - For sensors with connectors, make the connection. For instruments with pigtails, run the cable to a junction box in a suitable location to connect to your system.
  - For IRU-2002 and IRU-2003 sensors, system wiring must be connected to internal terminal strips prior to physical installation. (See Figures 2.1 and 2.2)

  ![NOTE: Please see wiring diagrams in Chapter 1 for RST Module Programming Wiring and other special wiring configurations.]

• **Software Installation**
  
  - Download the RST-3002 software zip file from [http://apgsensors.com/support](http://apgsensors.com/support).
  - Open the zip file.
  - Choose “Install” from the options at the top of the zip file window.
  - The installation process will prompt you as needed to complete the installation.
  - The software will create I2000SWR.exe which will run from a folder in your start menu titled “APG/I2000SWR”.

  ![IMPORTANT: RST-3002 is compatible with computers running 32- and 64-bit Windows systems.]

• **Removal Instructions**
  
  - Ensure that power to the sensor is off
  - Disconnect cable to sensor.
  - Remove the sensor and store it in a dry place, at a temperature between -40° F and 180° F.
  - If the sensor was installed in a hazardous location, ensure that the cable will not energize while the sensor is disconnected.

  ![DANGER: Do not disconnect equipment installed in hazardous locations unless power has been switched off or area is known to be non-hazardous.]
Chapter 3: Set Up and Operation

- User Interface

IRU sensors use one of two methods for user interface: RS-232 serial communications (IRU-6429S and IRU-9429S) or I2000SWR, the Windows-based utility software (all other models).

RS-232 Serial Communication

Sensors with the built-in RS-232 communications will accept one ASCII command (SEND), and return distance and temperature values in ASCII. When the sensor receives the SEND command (all capital letters), the sensor will transmit the distance in feet, followed by a comma, and then the temperature in degrees Celsius, followed by a carriage return and line feed. The distance will be five characters (e.g. 05.25) and the temperature will have a + or - followed by one or two characters (e.g. +22).

**IMPORTANT:** The sensor will return ASCII characters, not numeric values.

**NOTE:** If your sensor is turned off between readings, you must allow time for the sensor to initialize and process readings through filtering parameters before polling for output readings with a SEND command. Depending on your filter settings, this can take between 3 and 30 seconds, or longer.
Windows-based Utility Software: I2000SWR

I2000SWR software user interface is one screen with three primary areas (See Figure 3.1). The primary portion of the screen is two columns of Sensor Parameters. The Sensor Readings and Communication Status area is below the Sensor Parameters, in two uneven columns. Finally, the Control Buttons area is located across the bottom of the screen.

Only the fields in the Sensor Parameters are editable by the user. All of the fields in the Sensor Readings and Communication Status area are display only.

![Image of I2000SWR software user interface](image)

**Figure 3.1**
When the I2000SWR software is started it will attempt to establish communications with your IRU sensor via the RST-3002 module. The Send button will grey-out and the Sensor Communication Status will display “Receiving all data!!” During this initial communication, the software will determine the model number of your sensor (IRU-XXXX), configure the available parameters accordingly, and load the current parameter values from the sensor.

If the sensor model in the upper left-hand corner of the window does not change from the default (IRU-2003), then a communication error has occurred. Check all wiring to ensure proper connections have been made (See Figure 1.3). Then close (Exit) the software and open it again.

Changes to parameters are written to the sensor by clicking on the Send button. During the writing process, the Sensor Communication Status will display “Sending all data!!” The message will then change to “Communication Error!!” and the parameter fields will briefly change to green. The fields will then blank to white and the Sensor Communication Status will display “Receiving all data!!” At this point the parameter fields will turn greyish-blue and be populated with the new values read from the sensor.

The “Communication Error!!” message in this process is a result of the brief time needed for the sensor to switch from receiving the new parameters to sending all the parameters back to the software. As long as your changes are reflected in the final read of the sensor data, there has not been an actual communication error.
• **IRU Sensor Parameters**

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Units</td>
<td>Feet</td>
</tr>
<tr>
<td></td>
<td>Inches</td>
</tr>
<tr>
<td></td>
<td>mm</td>
</tr>
</tbody>
</table>

*Units* is used to select the units of measurement for parameter display. The units will also determine the resolution of the display and the outputs. The resolution is: feet 0.01, inches 0.1, and millimeters 1. When a new unit of measure is selected, the software will automatically communicate with the sensor and update appropriate parameters.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Blanking</td>
<td>Determined by sensor model</td>
</tr>
</tbody>
</table>

*Blanking* sets the blanking distance, which is the zone from the Zero Point of the sensor to the point from which the first echo will be accepted. While blanking distance can be used to ignore unwanted targets—such as welds, seams, pipe fittings, or gaskets—between the sensor and the closest acceptable target level, such objects generally create additional reflections and echoes, which are hard to filter out. More often, blanking distance is used for a sensor installed in a stand pipe.

Because of the physical properties of an ultrasonic sensor, objects cannot be detected closer than approximately 1 foot from the face of most transducers (4 inches for IRU-5XXX, and 6 inches for IRU-942X). However, this distance varies according to how much energy is being transmitted (*Pulses*) and the installation.

⚠️ **IMPORTANT:** *Blanking* is always measured from the Zero Point of the sensor. See Figures 3.4 - 3.6.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sensitivity</td>
<td>0 - 100%</td>
</tr>
</tbody>
</table>

*Sensitivity* sets the level of gain that is applied to the echo. When operating in AutoSense, Hard-Target, or Soft-Target (see *Gain Control*), *Sensitivity* sets an upper limit for the amplification that can be applied to the echo. If operating in Manual, this parameter sets the gain.

When using manual gain control, set *Sensitivity* to the minimum value that will allow the target to be reliably tracked through the full range of expected environmental conditions.
PARAMETER | RANGE
Sens/Trip Control | 0 = manual (potentiometer)
IRU-2002, IRU-2003 only | 1 = program (software)

For IRU-2002 sensors, Sensitivity/Trip Point Control is used to select between potentiometer or software control of Sensitivity and Relay Trip Point. (See Figure 2.1)

For IRU-2003 sensors, Sensitivity/Trip Point Control is used to select between potentiometer or software control of Sensitivity. (See Figure 2.2)

![Figure 3.3](image)

PARAMETER | RANGE
Pulses | 0-20

Pulses sets the maximum number of pulses the sensor can transmit when operating in AutoSense, Hard-Target, or Soft-Target (see Gain Control), or sets the number of pulses when operating in Manual. The more pulses that are sent in a burst, the stronger the returning echo.

When operating in Manual, increase the strength of the transmission by increasing Pulses for detecting soft targets in damping environments. In acoustically active environments or small enclosed areas, decrease Pulses to reduce multiple echoes.

PARAMETER | RANGE
Gain Control | 0 = Manual
1 = AutoSense
2 = Hard-Target
3 = Soft-Target

Gain Control selects the control mode for the sensor’s gain settings (Sensitivity and Pulses). In AutoSense, the sensor automatically adjusts the sensitivity and pulses for the best quality return signal. Manual, Hard Target, and Soft Target are user controlled scenarios. In Manual, the user is in full control of Sensitivity and Pulses. For Hard and Soft Target, the user sets maximum Sensitivity and Pulses, but the overall gain is either ramped up slowly (Hard Target) or quickly (Soft Target) by the sensor.

PARAMETER | RANGE
Average | 1-32

Average sets the number of qualified received signals to average for the displayed reading. Qualified received signals are placed in a first-in, first-out buffer, the contents of which are averaged for the displayed output. The larger the number of qualified received signals being averaged, the smoother the output reading will be, and the slower the reading will be to react to quickly changing targets.
**PARAMETER** | **RANGE**
--- | ---
Window | Determined by sensor model

*Window* determines the physical range of qualified received signals, based on the current reading. Signals beyond the +/- *Window* range of the current reading will not qualify unless the average moves. Signals outside the extents of the *Window* are written to the *Out of Range Samples* buffer.

**PARAMETER** | **RANGE**
--- | ---
Out of Range Samples | 0-250

*Out of Range Samples* sets the number of consecutive samples outside the *Window* necessary to automatically adjust the current reading and move the *Window*.

**PARAMETER** | **RANGE**
--- | ---
Sample Rate | 1 Hz to sensor Maximum

*Sample Rate* is the number of samples taken by the sensor every second. While higher sample rates allow for quicker sensor response times to changing levels, lower sample rates reduce the likelihood of echo-based false positives. Also, lower sample rates result in longer sensor life.

**PARAMETER** | **RANGE**
--- | ---
Multiplier | 0 - 1.999

*Multiplier* is used to calibrate the sensor for variations in the speed of sound due to variations in atmospheres. The default of 1.000 is used for most applications. See the Calibration section of Chapter 4.

---

**Figure 3.4**

---

**Figure 3.5**

---

**Figure 3.6**

---

**PARAMETER** | **RANGE**
--- | ---
Offset | -10 ft - + 10ft

*Offset* is used to change the Zero Point of the sensor. This is not the zero output (4 mA, 0 V, etc.) point of the sensor. The Zero Point of the sensor is the point from which the calculated distance is measured. When the Offset is set to 0, the Zero Point of the sensor is at the face of the transducer (See Figure 3.4). A positive setting will move the Zero Point forward, in front of the sensor face (See Figure 3.5). Setting the Offset to a negative number will move the Zero Point backward, behind the sensor face (See Figure 3.6).

In all cases, Blanking is measured from the end of Offset, and the effective measurement zone of the sensor begins at the forward end of Blanking. If Offset is more negative than Blanking is positive, the net difference will be a loss in sensor maximum range (See Figure 3.6).
### PARAMETER | RANGE
---|---
Temp Comp. | 0 = Off  
| 1 = On

*Temperature Compensation* activates or deactivates the IRU's internal temperature compensation circuit. The speed of sound changes with changes in temperature, therefore changes in temperature can affect distance measurements. These effects can be minimized by activating temperature compensation.

#### NOTE: If the internal temperature compensation is enabled and the sensor is exposed to direct sun light, the radiant heat can warm the sensor housing above the ambient temperature, which can affect the internal temperature sensor and cause overcompensation.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max Distance</td>
<td>Determined by sensor model</td>
</tr>
</tbody>
</table>

*Maximum Distance* sets the maximum acceptable signal range for the sensor, measured from the Zero Point. Signals beyond the *Maximum Distance* are ignored. Under Loss of Echo conditions, the software distance reading will display the *Maximum Distance*.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>View Noise Level</td>
<td>0 - 100</td>
</tr>
</tbody>
</table>

*View Noise Level* displays the number of echoes being picked up by the sensor. The presence of more than 30 echoes often indicates a noise source (acoustical or electrical) that could hamper sensor operation. Reducing the *Sensitivity* and *Pulses* may help cut down the influence of noise.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Set Noise Threshold</td>
<td>0 - 100</td>
</tr>
</tbody>
</table>

*Set Noise Threshold* sets an activation level for the sensor's noise filter. When the noise level exceeds the threshold, the filter activates a steady reading on the sensor until the noise level returns below the threshold. If periodic, short-term noise sources are known to be operating near the sensor, this threshold can be set to prevent false readings during noise-source activities.
PARAMETER: 4 MA Set Point
RANGE: 0 - Sensor Max Distance
Sensor Models with 4-20 mA output only

4 mA Set Point sets the distance at which the output is 4 mA. This distance is measured from the Zero Point. See Figures 3.3 and 3.4.

PARAMETER: 20 MA Set Point
RANGE: 0 - Sensor Max Distance
Sensor Models with 4-20 mA output only

20 mA Set Point sets the distance at which the output is 20 mA. This distance is measured from the Zero Point. See Figures 3.7 and 3.8.

For Distance configuration (i.e., greater mA output for target surface further from sensor), set the 4 mA Set Point to be less than the 20 mA Set Point. See Figure 3.7.
For Fill configuration (i.e., greater mA output for target surface closer to sensor), set the 4 mA Set Point to be greater than the 20 mA Set Point. See Figure 3.7.

PARAMETER: 0 VDC Set Point
RANGE: 0 - Sensor Max Distance
Sensor Models with 0-2.5 / 0-5 VDC output only

0 VDC Set Point sets the distance at which the output is 0 VDC. This is measured from the Zero Point. (See Figures 3.9 and 3.10)
<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 VDC Set Point</td>
<td>0  -  Sensor Max Distance</td>
</tr>
<tr>
<td>2.5 VDC Set Point</td>
<td>0  -  Sensor Max Distance</td>
</tr>
</tbody>
</table>

Sensor Models with 0-2.5 / 0-5 VDC output only

*5 VDC Set Point* and *2.5 VDC Set Point* set the distance at which the output is high voltage (2.5 or 5 VDC). This is measured from the Zero Point (See Figures 3.9 and 3.10). Use the *Max Voltage* parameter to select the high voltage output.

For Distance configuration (i.e., greater VDC output for target surface further from sensor), set the *0 VDC Set Point* to be less than the *2.5/5 VDC Set Point*. (See Figure 3.9)

For Fill configuration (i.e., greater VDC output for target surface closer to sensor), set the *0 VDC Set Point* to be greater than the *2.5/5 VDC Set Point*. (See Figure 3.9)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max Voltage</td>
<td>0  -  2.5V</td>
</tr>
<tr>
<td></td>
<td>1  -  5V</td>
</tr>
</tbody>
</table>

Sensor Models with 0-2.5 / 0-5 VDC output only

*Max Voltage* selects the maximum DC voltage sourced on the analog output. (See Figure 3.10)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 Volt Calibrate</td>
<td>0  -  4096</td>
</tr>
<tr>
<td>2.5 Volt Calibrate</td>
<td>Default: 4095</td>
</tr>
</tbody>
</table>

Sensor Models with 0-2.5 / 0-5 VDC output only

*5 Volt Calibrate* and *2.5 Volt Calibrate* fine tune the maximum DC voltage sourced on the analog output.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 MA Calibrate</td>
<td>0  -  65534</td>
</tr>
<tr>
<td></td>
<td>Default: 8200</td>
</tr>
</tbody>
</table>

Sensor Models with 4-20 mA output only

*4 mA Calibrate* fine tunes the minimum current sourced on the analog output. (See Figure 3.8)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>20 MA Calibrate</td>
<td>0  -  65534</td>
</tr>
<tr>
<td></td>
<td>Default: 41000</td>
</tr>
</tbody>
</table>

Sensor Models with 4-20 mA output only

*20 mA Calibrate* fine tunes the maximum current sourced on the analog output. (See Figure 3.8)
• **Relay and NPN Trip Output Configuration**

Along with, or instead of, an analog output, some IRU sensors have relay (IRU-2002) or NPN Trip (IRU-2004, IRU-XXX5) outputs. The relay or NPN can be configured to turn on or off based on the measurement of the sensor. (See Figure 3.11)

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Trip Distance</td>
<td>0 - Sensor Max Distance</td>
</tr>
</tbody>
</table>

*Trip Distance* sets the distance to the trip position closest to the sensor face.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>RANGE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Trip Window</td>
<td>0 - Sensor Max Distance</td>
</tr>
</tbody>
</table>

*Trip Window* sets the distance from the first trip position to the trip position farthest from the sensor face.

**Trip Type**

0 - *Near*

*Near* activates the output whenever the target surface is closer than the *Trip Distance* setting.

1 - *Exclusive*

*Exclusive* activates the output whenever the target surface is closer than the *Trip Distance* setting OR beyond the *Trip Distance + Trip Window* setting.
**Trip Type**

2 - Hysteresis Near

*Hysteresis Near* activates the output whenever the target surface moves closer than the *Trip Distance* setting. The output remains activated until the target surface moves beyond the *Trip Distance* + *Trip Window* setting. The output remains off until the target surface moves closer than the *Trip Distance* setting again.

**Trip Type**

3 - Far

*Far* activates the output whenever the target surface is beyond the *Trip Distance* setting.

**Trip Type**

4 - Inclusive

*Inclusive* activates the output whenever the target surface is beyond the *Trip Distance* setting AND closer than the *Trip Distance* + *Trip Window* setting.

**Trip Type**

5 - Hysteresis Far

*Hysteresis Far* activates the output whenever the target surface moves beyond the *Trip Distance* + *Trip Window* setting. The output remains activated until the target surface moves closer than the *Trip Distance* setting. The output remains off until the target surface moves beyond the *Trip Distance* + *Trip Window* setting again.

**Sensor Readings and Communication Status**

Below the Sensor Parameters and Output Configuration is the Sensor Readings and Communication Status area. On the left side are three sensor reading displays: Distance, Temperature, and Analog Output (current or voltage). On the right side are three or four communication status displays: *USB status*, *Trip 1*, *Trip 2*, or *Relay Status* (depending on sensor model), *Sensor Communication Status*, and *Signal Strength Status*. (See Figure 3.13)
Reading Type: Distance

Distance displays the current output of the sensor in the units selected in the Units parameter above.

Reading Type: Temperature

Temperature displays the current temperature of the thermal device in the IRU sensor body.

Reading Type: Analog Output

Analog Output displays the current analog output (all models except IRU-2002 and IRU-2004) of the sensor.

Communication Type: USB Status

USB Status displays the status of the USB connection between the I2000SWR software and the RST-3002 as detected when the software initiated.

Communication Type: Trip Status

Trip Status displays the status of the relay (IRU-2002), NPN Trip (IRU-2004), or NPN Trips (IRU-XXX5).

Communication Type: Sensor Com Status

Sensor Communication Status displays the current status of communication between the I2000SWR and the IRU sensor. Typically this box is blank. The three messages--“Receiving all data!!”, “Sending all data!!”, and “Communication Error!!!”--only display while their respective events are happening.
**Communication Type** | **Range**
--- | ---
*Signal Strength Status* | 0 - 7
| Default

*Signal Strength Status* displays the strength of the signal being received by the sensor. 0 represents the highest quality signal, and 7 represents the lowest quality. For some sensor models, the *Signal Strength Status* may show “Default” if the sensor is not fully communicating with the I2000SWR software. Other models only display “Default,” and never show the 0-7 range.

- **Control Buttons**

Below the Sensor Readings and Communication Status area are four Control Buttons. On the left side are three sensor communication buttons: Send, Receive, and Reset. In the middle are a dropdown box and check box for selecting the communication channels. On the right side is the Exit button. (See Figure 3.14)

![Control Buttons](image)

**Figure 3.14**

**Control Button**

*Send*

Send sends all the user-entered values for sensor parameters to the sensor. After sending the parameters to the sensor, the software will automatically poll the sensor to receive back all parameters. The *Sensor Communication Status* display will show the progression of the writing and reading of sensor parameters.

**Control Button**

*Receive*

Receive polls the IRU sensor to read all the sensor parameters into the software. The Sensor Communication Status display will show the progression of the reading of sensor parameters.

**Control Button**

*Reset*

Reset returns all sensor parameters to their factory settings. After resetting the parameters on the sensor, the software will automatically poll the sensor to receive back all parameters The *Sensor Communication Status* display will show the progression of the resetting and reading of the sensor parameters.
### Dropdown Box

<table>
<thead>
<tr>
<th>Range</th>
<th>Com Channel</th>
</tr>
</thead>
<tbody>
<tr>
<td>No Selection</td>
<td>1</td>
</tr>
</tbody>
</table>

*Com Channel* selects the computer’s communication port used for RS-232 serial communication between the I2000SWR software and the IRU sensor. If you are using an RST-3002 via USB you do not need to use this dropdown box.

### Check Box

*USB*

The *USB* checkbox directs the I2000SWR software to use communicate with the IRU sensor via USB and an RST module. If the box is unchecked, the software will use RS-232 via the selected com port in the *Com Channel* dropdown box.

### Control Button

*Exit*

*Exit* closes the I2000SWR software. Sensor parameters that have been successfully written to the sensor will be stored in non-volatile memory on the IRU.

### Saving and Loading Parameter Files

In the File Menu are options for saving and loading parameters in text (.txt) files. **Save Parameters** will write the current values for all parameters in the I2000SWR software to a .txt file. **Load Parameters** will load all the parameters in a .txt file into the I2000SWR software. The parameters will not be written to the IRU until the **Send** button is clicked. Similarly, to ensure that the current parameters in the IRU are written to a file, **Receive** must be clicked before choosing File>Save Parameters.

Saving and loading parameters is especially helpful for setting up several identical sensors in identical settings. Once the parameters for the first sensor are configured appropriately, the parameters can be saved in a .txt file and subsequently loaded into the remaining sensors.
Chapter 4: Maintenance

• General Care

Your IRU ultrasonic sensor is very low maintenance and will need little care as long as it was installed correctly. However, in general, you should:

• Avoid applications for which the sensor was not designed, such as extreme temperatures, contact with incompatible corrosive chemicals, or other damaging environments.
• Inspect the threads whenever you remove the sensor from duty or change its location (for sensors with NPT threads).

• Trouble Shooting

Should you have problems with your IRU, here are some troubleshooting steps.

• Check the Signal Strength Status (See Figure 3.9 on page 26 and explanation on page 27). If the signal strength is low, alternately increase Pulses and Sensitivity (pages 18 and 19) until the signal strength improves.
• Ensure Temperature Compensation (page 21) is turned on.
• Set Gain Control (page 19) to AutoSense.
• Ensure that Blanking (page 18) is accurately set to account for any unwanted targets between the sensor and the closest acceptable target.
• Ensure that the Noise Threshold is greater than the Noise Level (page 21).
• Ensure that the settings for Average and Window (pages 19 and 20) allow for anticipated target surface movement without adversely effecting the output reading.

• Calibration

This procedure uses targets at known distances to calibrate the sensor’s accuracy. A wall or other large, flat object is recommended for the long range target.

• Point the sensor at a target at a known distance near the maximum range of the sensor (See Figure 4.1).
• Adjust the Multiplier until the distance reading on the sensor matches the actual measured distance to the target.
• Point the sensor at a target near the minimum measurement range plus any Blanking distance (See Figure 4.2).
• Adjust the Offset value until the distance reading on the sensor matches the actual measured distance to the target.
• Repeat previous two steps until no further adjustment is required.
NOTE: The Reset button in the I2000SWR software will reset the IRU to factory default settings (See Figure 3.14).

• **Repair and Returns**

Should your IRU ultrasonic sensor require service, please contact the factory via phone, email, or online chat. We will issue you a Return Material Authorization (RMA) number with instructions.

- Phone: 888-525-7300
- Email: sales@apgsensors.com
- Online chat at www.apgsensors.com

Please have your IRU sensor’s part number and serial number available. See Warranty and Warranty Restrictions for more information.
Installation In Class I Division 2 Groups C and D
Class I Zone 2 A Ex nA IIB

Hazardous Area

Non-Hazardous Area

- Install in accordance with Section 18 of the CEC or Article 500 of the NEC.
- CSA listed or NRTL/UL listed conduit seal at location A & B.
- The cable is potted into the sensor and runs continuously from the sensor through the Hazardous area and into the Non-Hazardous area.
- Electrical equipment connected to associated apparatus should not generate more than 250 V rms.
- Tampering or replacement with non-factory components may adversely affect the safe use of the system.
- WARNING: DO NOT DISCONNECT WHILE CIRCUIT IS ALIVE UNLESS AREA IS KNOWN TO BE NON-HAZARDOUS
- Avertissement: Ne pas débrancher tant que le circuit est sous tension, à moins qu'il ne s'agisse d'un emplacement non dangereux.

WARNING: POTENTIAL ELECTROSTATIC CHARGING HAZARD - Clean only with a damp cloth.
The products listed below are eligible to bear the CSA Mark shown with adjacent indicators 'C' and 'US' for Canada and US or with adjacent indicator 'US' for US only or without either indicator for Canada only.

Issued by: Ron Wachowicz, C.E.T.

Authorized by: Gary Boswell, P.Eng., Product Group Manager

PRODUCTS
CLASS 2252 03 - PROCESS CONTROL EQUIPMENT
CLASS 2252 83 - PROCESS CONTROL EQUIPMENT - Certified to US Standards
CLASS 2258 02 - PROCESS CONTROL EQUIPMENT - For Hazardous Locations
CLASS 2258 82 - PROCESS CONTROL EQUIPMENT - For Hazardous Locations - Certified to US Standards

CLASS 2252 03 – PROCESS CONTROL EQUIPMENT
CLASS 2252 83 – PROCESS CONTROL EQUIPMENT – To U.S. Requirements


** designates the color of the housings BK = black, RD = red, default = blue

DST Series Ultrasonic Sensor Models DST-2421, DST-3431, DST-5111 and DST-9421 input Rated 12 to 28Vdc, 60mA max; Ambient temperature range -30°C to +60°C.

NOTE: The above models are Pollution Degree 2, Installation Category II.

CLASS 2258 02 – PROCESS CONTROL EQUIPMENT – For Hazardous Locations

CLASS 2258 82 – PROCESS CONTROL EQUIPMENT – For Hazardous Locations – To U.S. Requirements

Class I, Division 2, Groups C and D, T6; Ex nA IIB T6 (Canada), IP65; Class I, Zone 2; AEx nA IIB, T6 (USA), IP65:

IRU Series Ultrasonic Sensors, Models IRU-2125, IRU-3135, IRU-2423, IRU-2425, IRU-3433, IRU-3435, IRU-5413, IRU-5415, IRU-5423, IRU-5425 and IRU-5429; input Rated 12 to 28Vdc, 80mA max; Outputs 4-20mA, NPN; Ambient temperature range -30°C to +60°C.

NOTE: The above models are Pollution Degree 2, Installation Category II.

APPLICABLE REQUIREMENTS

C22.2 No 0 - M1991 - General Requirements - Canadian Electrical Code Part II.
C22.2 No 0.4 - M1982 - Bonding and Grounding of Electrical Equipment (Protective Grounding).
C22.2 No 213 - M1987 - Non-Incendive Electrical Equipment for Use in Class I, Division 2 Hazardous Locations.
CAN/CSA-C22.2 No. 1010.1-92 - Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use, Part 1: General Requirements (Includes Amendment 1)
CAN/CSA-C22.2 No. 1010.1B 97 - Amendment 2 to CAN/CSA C22.2 No. 1010.1 92, "Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use, Part 1: General Requirements"
T.I.L. No I-29 - Additional Requirements For Process Control Equipment Certified to CSA Standard CAN/CSA C22.2 No 1010.1-92
Certificate: 1384697

Project: 2166699

Master Contract: 237484

Date Issued: 2010/02/19

ISA S82.01-1994 - Safety Standards for Electrical and Electronic Test, Measuring, Controlling, and Related Equipment - General Requirements

CAN/CSA E60079-0:07 - Electrical apparatus for explosive gas atmospheres - Part 0 - General requirements.

CAN/CSA E60079-15:02 - Electrical Apparatus for Explosive Gas Atmospheres - Part 15-Type of Protection n.

UL 1604, Third Edition - Electrical Equipment for Use in Class I and II, Division 2, And Class III Hazardous (Classified) Locations.

UL 60079-0, 4th Ed. - Electrical Apparatus for Explosive Gas Atmospheres - Part 0 - General Requirements.

UL 60079-15, 1st Ed. - Electrical Apparatus for Explosive Gas Atmospheres - Part 15 - Electrical Apparatus with Type of Protection n.